

A Compound Class of Geometric and Lifetimes Distributions

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Abstract: A new lifetime class with decreasing failure rates is introduced by compounding truncated Geometric distribution and any proper continuous lifetime distribution. The properties of the proposed class are discussed, including a formal proof of its probability density function, distribution function and explicit algebraic formulae for its reliability and failure rate functions. A simple EM-type algorithm for iteratively computing maximum likelihood estimates is presented. A formal equation for Fisher information matrix is derived in order to obtain the asymptotic covariance matrix. This new class of distributions generalizes several distributions which have been introduced and studied in the literature.

Keywords: Lifetime distributions, decreasing failure rate, Geometric distribution.

1. INTRODUCTION

The study of life time organisms, devices, structures, materials, etc., is of major importance in the biological and engineering sciences. A substantial part of such study is devoted to the mathematical description of the length of life by a failure distribution. Sometimes physical considerations of the failure mechanism may lead to a specific distribution but more often, the choice is made on the basis of how well the actual observations of times to failure appear to be fitted by the distribution. In reliability studies a useful tool for reducing the range of possible candidates is provided by the shape and monotonicity of the failure rate function since it reflects some of the characteristics of the mechanism leading to life conclusion.

Situations where the failure rate function decreases with time have been reported by several authors. Indicative examples are business mortality [1], failure in the air-conditioning equipment of a fleet of Boeing 720 aircrafts or in semiconductors from various lots combined [2] and the life of integrated circuit modules [3]. In general, a population is expected to exhibit a decreasing failure rate (DFR) when its behavior over time is characterized by 'work hardening' (in engineering terms) or 'immunity' (in biological terms); sometimes the broader term 'infant mortality' is used to denote the DFR phenomenon. The resulting improvement of reliability with time might have occurred by means of actual physical changes that caused self-improvement or simply it might have been due to population heterogeneity. Indeed, [2] provided that the DFR property is inherent to mixtures of distributions with constant failure rate [4] for other properties of exponential mixtures [5], demonstrated the converse for any gamma distribution with shape parameter less than one. In addition, [6] give examples illustrating that such results may hold for mixtures of distributions with rapidly increasing failure rate. A mixture of truncated geometric distribution

and exponential with DFR was introduced by [7]. The exponential-Poisson (EP) distribution was proposed by [8] and generalized [9] using Weibull distribution and the exponential-logarithmic distribution discussed by [10]. A two-parameter distribution family with decreasing failure rate arising by mixing power-series distribution has been introduced [11]. A Weibull power series class of distributions with Poisson presented [12, 13] in a master degree thesis presented a class of generalized Beta distributions, Pareto power series and Weibull power series. Lately [14], obtained a class of truncated Poisson with any continuous lifetime distribution.

A further exponentiated type distribution has been introduced and studied in the literature. The exponential Weibull (EW) distribution was proposed [15] to extend the geometric exponential (GE) distribution. This distribution was also studied [16-19] introduced four more exponentiated type distributions: the exponentiated gamma, exponentiated Weibull, exponentiated Gumbel and exponentiated Fréchet distributions by generalizing the gamma, Weibull, Gumbel and Fréchet distributions in the same way that the GE distribution extends the exponential distribution. In a recent paper, [20] introduced the generalized exponential-Poisson distribution which extends the exponential-Poisson distribution in the same way that the GE distribution extends the exponential distribution.

In this paper we generalize the work of [7] to a class of several lifetime continuous distributions. This paper is organized as follows. In Section 2, the new class of geometric lifetime distributions with its probability and distribution functions are introduced. In Section 3, the corresponding survival and hazard rate functions with some of their properties are derived. In Section 4, maximum likelihood estimate of the unknown parameters are obtained based on a random sample *via* EM algorithm. In Section 5, the entropy for the geometric lifetime distributions class is discussed.

2. THE CLASS

Given Z , let T_1, \dots, T_Z be independent and identically distributed (iid) random variables with probability density function (pdf) given by

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$$f_{T_i}(x; \underline{\theta}) = f_T(x; \underline{\theta}); \underline{\theta} = (\theta_1, \dots, \theta_k), k \geq 1, x, \underline{\theta} \in \mathbb{R}^+$$

Here, Z is a zero truncated Geometric random variable with probability mass function given by

$$f_Z(z; p) = (1 - p)p^{z-1}, z \in \mathbb{N}, 0 < p < 1,$$

where

Z and $T_i, i = 1, \dots, Z$ are independent random variables. Let $X = \min(T_1, \dots, T_Z)$ then, the pdf of the random variable X is obtained as

$$f_X(x; p, \underline{\theta}) = \frac{(1 - p)f_T(x; \underline{\theta})}{[1 - p(1 - F_T(x; \underline{\theta}))]^2} \tag{1}$$

and hence the cumulative distribution function (cdf) of X is

$$F_X(x; p, \underline{\theta}) = \frac{F_T(x; \underline{\theta})}{1 - p(1 - F_T(x; \underline{\theta}))} \tag{2}$$

The proof of the results in (1) and (2) is presented in the following theorem.

Theorem 2.1. Suppose that T_1, \dots, T_Z with $f_{T_i}(x, \underline{\theta}) = f_T(x, \underline{\theta}), \underline{\theta} = (\theta_1, \dots, \theta_k)$ for $k \geq 1, x, \underline{\theta} \in \mathbb{R}^+$ and Z is a zero truncated Geometric variable with probability mass function $f_Z(z; p) = (1 - p)p^{z-1}, z \in \mathbb{N}, 0 < p < 1$ where Z and $T_i, i = 1, \dots, Z$ are independent random variables. If $X = \min(T_1, \dots, T_Z)$ then the pdf and cdf of X are

$$f_X(x; p, \underline{\theta}) = \frac{(1 - p)f_T(x; \underline{\theta})}{[1 - p(1 - F_T(x; \underline{\theta}))]^2}$$

and

$$F_X(x; p, \underline{\theta}) = \frac{F_T(x; \underline{\theta})}{1 - p(1 - F_T(x; \underline{\theta}))}$$

respectively.

Proof: By definition, the pdf of X given $Z = z$ is

$$f_{X|Z}(x; \underline{\theta}) = \frac{f_{X,Z}(x, z; p, \underline{\theta})}{f_Z(z)} = z f_T(x; \underline{\theta}) [1 - F_T(x; \underline{\theta})]^{z-1},$$

and hence the joint pdf of X and Z is obtained as

$$\begin{aligned} f_{X,Z}(x, z; p, \underline{\theta}) &= f_Z(z) f_{X|Z}(x; \underline{\theta}) \\ &= (1 - p)p^{z-1} z f_T(x; \underline{\theta}) [1 - F_T(x; \underline{\theta})]^{z-1}. \end{aligned}$$

The marginal pdf and cdf of X are given by

$$f_X(x; p, \underline{\theta}) = \sum_{z=1}^{\infty} f_{X,Z}(x, z; p, \underline{\theta})$$

$$\begin{aligned} &= (1 - p) f_T(x; \underline{\theta}) \sum_{z=1}^{\infty} z [p(1 - F_T(x; \underline{\theta}))]^{z-1} \\ &= \frac{(1 - p) f_T(x; \underline{\theta})}{[1 - p(1 - F_T(x; \underline{\theta}))]^2} \end{aligned}$$

and

$$\begin{aligned} F_X(x; p, \underline{\theta}) &= \int_0^x f_X(x; p, \underline{\theta}) dx = \int_0^x \frac{(1 - p) f_T(x; \underline{\theta})}{[1 - p(1 - F_T(x; \underline{\theta}))]^2} dx \\ &= \frac{F_T(x; \underline{\theta})}{1 - p(1 - F_T(x; \underline{\theta}))} \end{aligned}$$

respectively.

We denote a random variable X with pdf and cdf (1) and (2) by $X \sim GL(p, \underline{\theta})$. This new class of distributions generalizes several distributions which have been introduced and studied in the literature. For instance using the probability density and its distribution function of exponential distribution in (1), we obtain the exponential geometric distribution [7] and using Weibull probability density and its distribution function gives Weibull geometric distribution [21]. The model is obtained under the concept of population heterogeneity (through the process of compounding). An interpretation of the proposed model is as follows: a situation where failure (of a device for example) occurs due to the presence of an unknown number, Z , of initial defects of same kind (a number of semiconductors from a defective lot, for example). According to [7], the T s represent their lifetimes and each defect can be detected only after causing failure, in which case it is repaired perfectly. Then the distributional assumptions given earlier lead to any of the GL distributions for modeling the time to the first failure X .

Table 1 shows the probability function and the distribution function for some lifetime distributions.

Some of the other lifetime distributions are excluded from this table since they do not have nice forms such as Gamma and lognormal distributions although they still can be applied in this class numerically.

The q th quantile x_q of the GL distribution, the inverse of the distribution function $F_X(x_q) = q$ is the same as the inverse of the distribution function $F_T(x_q) = \frac{q(1-p)}{1-pq}$ for any continuous lifetime with distribution function $F_T(\cdot)$.

3. SURVIVAL AND HAZARD FUNCTIONS

Since the GL is not a part of the exponential family, there are no simple form for moments see for instant (Kus[8]) for the exponential case. Survival function (also known reliability function) (sf) and hazard function (known as failure rate function) (hf) for the GL class are given in the following theorem.

Table 1. Probability and Distribution Functions

	$f_X(x; p, \underline{\theta})$	$F_X(x; p, \underline{\theta})$
Exponential	$\frac{(1-p)\lambda e^{-\lambda x}}{[1-pe^{-\lambda x}]^2}$	$\frac{1-e^{-\lambda x}}{1-pe^{-\lambda x}}$
Weibull	$\frac{(1-p)\alpha\beta(\beta x)^{\alpha-1}e^{-(\beta x)^\alpha}}{[1-pe^{-(\beta x)^\alpha}]^2}$	$\frac{1-e^{-(\beta x)^\alpha}}{1-pe^{-(\beta x)^\alpha}}$
Rayleigh	$\frac{(1-p)\theta^2 x e^{-\frac{\theta^2}{2}x^2}}{[1-pe^{-\frac{\theta^2}{2}x^2}]^2}$	$\frac{1-e^{-\frac{\theta^2}{2}x^2}}{1-pe^{-\frac{\theta^2}{2}x^2}}$
Pareto	$\frac{(1-p)\gamma(1+x)^{\gamma-1}}{[(1+x)^\gamma - p]^2}$	$\frac{(1+x)^\gamma - 1}{(1+x)^\gamma - p}$

Theorem 3.1 Suppose that T_1, \dots, T_Z are independent random variables with

$$f_{T_i}(x, \underline{\theta}) = f_T(x, \underline{\theta}), \quad \underline{\theta} = (\theta_1, \dots, \theta_k)$$

for $k \geq 1, x, \underline{\theta} \in \mathbb{R}^+$ and Z is a zero truncated Geometric random variable with probability mass function

$$f_Z(z; p) = (1-p)p^{z-1}, \quad z \in \mathbb{N}, \quad 0 < p < 1$$

where Z and $T_i, i=1, \dots, Z$ are independent random variables. If $X = \min(T_1, \dots, T_Z)$, then the sf and hf of X are

$$s_X(x; p, \underline{\theta}) = \frac{(1-p)s_T(x; \underline{\theta})}{1-ps_T(x; \underline{\theta})} \tag{3}$$

and

$$h_X(x; p, \underline{\theta}) = \frac{f_T(x; \underline{\theta})}{s_T(x; \underline{\theta})(1-ps_T(x; \underline{\theta}))} \tag{4}$$

respectively, where $s_T(x; \underline{\theta})$ is the survival function of any continuous lifetime distribution.

Proof: Using (1) and (2), survival function (also known reliability function) and hazard function (known as failure rate function) for the GL class are given respectively by

$$\begin{aligned} s_X(x; p, \underline{\theta}) &= 1 - F_X(x; p, \underline{\theta}) = 1 - \frac{F_T(x; \underline{\theta})}{1 - p(1 - F_T(x; \underline{\theta}))} \\ &= \frac{s_T(x; \underline{\theta}) - ps_T(x; \underline{\theta})}{1 - ps_T(x; \underline{\theta})} = \frac{(1-p)s_T(x; \underline{\theta})}{1 - ps_T(x; \underline{\theta})} \end{aligned}$$

and

Table 2. Survival and Hazard Functions

	$s_X(x; p, \underline{\theta})$	$h_X(x; p, \underline{\theta})$
Exponential	$\frac{(1-p)e^{-\lambda x}}{1-pe^{-\lambda x}}$	$\frac{\lambda}{1-pe^{-\lambda x}}$
Weibull	$\frac{(1-p)e^{-(\beta x)^\alpha}}{1-pe^{-(\beta x)^\alpha}}$	$\frac{\alpha\beta(\beta x)^{\alpha-1}}{1-pe^{-(\beta x)^\alpha}}$
Rayleigh	$\frac{(1-p)e^{-\frac{\theta^2}{2}x^2}}{1-pe^{-\frac{\theta^2}{2}x^2}}$	$\frac{\theta^2 x}{1-pe^{-\frac{\theta^2}{2}x^2}}$
Pareto	$\frac{1-p}{(1+x)^\gamma - p}$	$\frac{\gamma}{(1+x)^\gamma - p(1+x)^{1-\gamma}}$

$$\begin{aligned} h_X(x; p, \underline{\theta}) &= \frac{f_X(x; p, \underline{\theta})}{s_X(x; p, \underline{\theta})} = \frac{(1-p)f_T(x; \underline{\theta})}{[1-ps_T(x; \underline{\theta})]^2} \frac{1-ps_T(x; \underline{\theta})}{(1-p)s_T(x; \underline{\theta})} \\ &= \frac{f_T(x; \underline{\theta})}{s_T(x; \underline{\theta})(1-ps_T(x; \underline{\theta}))} \end{aligned}$$

Table 2 summarizes the survival functions and hazard rate functions for some distributions of the class.

The hazard function for GL class is decreasing because the DFR property follows from the result of Barlow *et al.* (1963) [22] on mixture.

4. ESTIMATION

In what follows, we discuss the estimation of the GL class parameters. Let x_1, \dots, x_n be a random sample with observed values x_1, \dots, x_n from a GL distribution with parameters p and $\underline{\theta}$. Let $\mathbb{E} = (p, \underline{\theta})$ be the parameter vector. The log log-likelihood function based on the observed random sample size of $n, y_{obs} = (x_1, \dots, x_n)$ is obtained by

$$\begin{aligned} \ell(p, \underline{\theta}; y_{obs}) &= n \log(1-p) + \sum_{i=1}^n \log f_T(x_i; \underline{\theta}) - 2 \sum_{i=1}^n \log(1-p(1-F_T(x_i; \underline{\theta}))) \end{aligned}$$

and the associated score function is given by

$$U_n(\underline{\mathbb{E}}) = \left(\frac{\partial \ell}{\partial p}, \frac{\partial \ell}{\partial \theta_1}, \dots, \frac{\partial \ell}{\partial \theta_k} \right), \text{ where}$$

$$\frac{\partial \ell(p, \underline{\theta}; y_{obs})}{\partial p} = -\frac{n}{1-p} + 2 \sum_{i=1}^n \frac{1-F_T(x_i; \underline{\theta})}{1-p(1-F_T(x_i; \underline{\theta}))} \tag{5}$$

and

$$\frac{\partial \ell(\underline{\mathbb{E}}; y_{obs})}{\partial \theta_i} = \sum_{i=1}^n \frac{1}{f_T(x_i; \underline{\theta})} \frac{\partial f_T(x_i; \underline{\theta})}{\partial \theta_i}$$

$$2p \sum_{i=1}^n \frac{\frac{\partial F_T(x_i; \underline{\theta})}{\partial \theta_i}}{1 - p(1 - F_T(x_i; \underline{\theta}))}, \quad i = 1, \dots, k \quad (6)$$

The maximum likelihood estimates (MLE) of Θ , say $\hat{\Theta}$, is obtained by solving the nonlinear system $U_n(\Theta) = 0$. The solution of this nonlinear system of equations has not a closed form, but can be found numerically by using software such as MATHEMATICA, MAPLE, Ox and R.

For interval estimation and hypothesis tests on model parameters, we require the information matrix. The $(k + 1) \times (k + 1)$ information matrix is given by

$$I_n(\Theta) = \begin{pmatrix} l''_{pp} & l''_{p\theta_i} \\ l''_{\theta_i p} & l''_{\theta_i \theta_i} \end{pmatrix}$$

where the elements of $I_n(\Theta)$ are the second partial derivatives of (5) and (6). Under the regular conditions stated in (Cox and Hinkley [23]), that are fulfilled for our model whenever the parameters are in the interior of the parameter space, we have that the asymptotic distribution of $\sqrt{n}(\hat{\Theta} - \Theta)$ is multivariate normal $N_{k+1}(0, k(\Theta)^{-1})$, where $k(\Theta) = \lim_{n \rightarrow \infty} n^{-1} I_n(\Theta)$ is the unit information matrix.

4.1. EM Algorithm

Based on the underlying distribution, the maximum likelihood estimation of the parameters can be found analytically using an EM algorithm. Newton–Raphson algorithm is one of the standard methods to determine the MLEs of the parameters. To employ the algorithm, second derivatives of the log-likelihood are required for all iteration. EM algorithm is a very powerful tool in handling the incomplete data problem (Dempster, Laird and Rubin [24, 25]). It is an iterative method by repeatedly replacing the missing data with estimated values and updating the parameter estimates. It is especially useful if the complete data set is easy to analyze. As pointed out by [26], the EM algorithm will converge reliably but rather slowly (as compared to the Newton–Raphson method) when the amount of information in the missing data is relatively large. Recently, EM algorithm has been used by several authors such as [7, 27-30].

To estimate Θ , EM algorithm is a recurrent method such that each step consists of an estimate of the expected value of a hypothetical random variable and later maximizes the log-likelihood of the complete data. Let the complete data be X_1, \dots, X_n with observed values x_1, \dots, x_n and the hypothetical random variable Z_1, \dots, Z_n . The joint probability function is such that the marginal density of X_1, \dots, X_n is the likelihood of interest. Then, we define a hypothetical complete-data distribution for each $(X_i, Z_i)^T, i = 1, \dots, n$,

With a joint probability function in the form

$$f_{X,Z}(x, z; \Theta) = (1 - p)p^{z-1} z f_T(x; \underline{\theta}) [1 - F_T(x; \underline{\theta})]^{z-1}$$

with $x, \underline{\theta} \in \mathbb{R}^+$, $0 < p < 1$ and $z \in \mathbb{N}$. Thus, it is straightforward to verify that the Estep of an EM cycle requires the computation of the conditional expectation of $(Z|X; \Theta^{(r)})$,

where $\Theta^{(r)} = (p^{(r)}, \underline{\theta}^{(r)})$ is the current estimate (in the r th iteration) of $\hat{\Theta}$. The EM cycle is completed with M-step, which is complete data maximum likelihood over (Θ) , with the missing Z 's replaced by their conditional expectations $E(Z|X; \hat{\Theta})$ (Adamidis and Loukas [7]), where

$$f_{Z|X}(z) = z [p(1 - F_T(x; \underline{\theta}))]^{z-1} [1 - p(1 - F_T(x; \underline{\theta}))]^2$$

and its expected value is

$$E(Z|X) = \frac{1 - p(1 - F_T(x; \underline{\theta}))}{p^2(1 - F_T(x; \underline{\theta}))^2}$$

5. ENTROPY FOR THE CLASS

If X is a random variable having an absolutely continuous cumulative distribution function $F_X(x)$ and probability distribution function $f_X(x)$ then the basic uncertainty measure for distribution F (called the entropy of F) is defined as $H_X(X) = -E(\log f(x))$, hence the general entropy form for the GL class is given

$$H_X(X) = -E(\log f(X)) = H_T(X) - \log(1 - p) + 2E[\log(1 - p(1 - F_T(x; \underline{\theta})))] \quad (7)$$

where $H_T(X)$ is the entropy of any lifetime distribution in the class. Note that as p increases the $H_X(X)$ increases too which is very logical since the increase of probability of accidents increases the entropy.

Statistical entropy is a probabilistic measure of uncertainty or ignorance about the outcome of a random experiment, and is a measure of a reduction in that uncertainty. Since [31] pioneering work on the mathematical theory of communication, entropy has been used as a major tool in information theory and in almost every branch of science and engineering. Numerous entropy and information indices, among them the Renyi entropy, have been developed and used in various disciplines and contexts. Information theoretic principles and methods have become integral parts of probability and statistics and have been applied in various branches of statistics and related fields.

CONFLICT OF INTEREST

The authors confirm that this article content has no conflicts of interest.

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